



# Deep Active Learning for Civil Infrastructure Defect Detection

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# Outline

- Importance of Defect Detection
- Previous Methods
- Problem Formulation
- Our solution
  - Deep Residual Network
  - Active Learning
- Results and Discussions



Bridges



Roads



Transit



<http://www.infrastructurereportcard.org/the-impact/explore-infographics/surface-transportation-infrastructure/>

AVERAGE AGE  
OF A BRIDGE:

**43**  
years

**9.1%**

IN 2016

**56,000**  
OF THE NATION'S BRIDGES WERE  
STRUCTURALLY DEFICIENT

**188 MILLION**  
TRIPS ARE TAKEN ON  
STRUCTURALLY DEFICIENT BRIDGES

# Inspection & Maintenance: Bridge



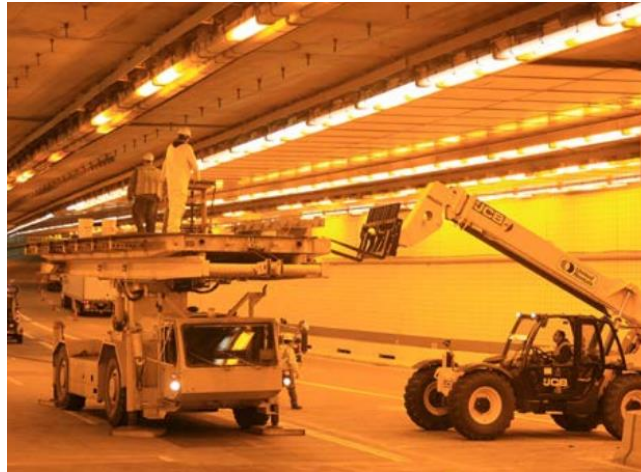


# Inspection & Maintenance: Bridge



(FHWA 2012, Bridge inspector's reference manual)

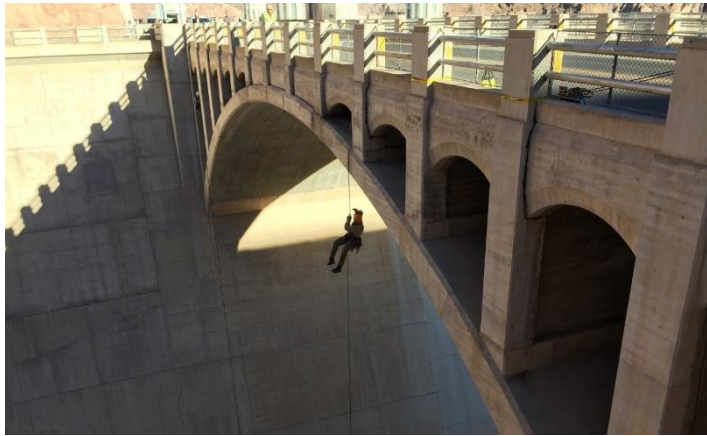
# Inspection & Maintenance: Tunnel



# Inspection & Maintenance: Dam



<http://www.ropeworks.com/service.htm>



<http://news3lv.com/news/local/gallery/hover-dam-concrete-spillways-need-different-safety-measures-than-oroville-dam-erosion#photo-2>



[https://www.usbr.gov/lc/region/feature/Rope\\_Access\\_Team\\_130628.html](https://www.usbr.gov/lc/region/feature/Rope_Access_Team_130628.html)



# Robots are coming!





# Robots are coming!



NYPA 2013



<http://www.xyht.com/aerialuas/multicopter-profiles/>



[http://echord.eu/essential\\_grid/arsi/](http://echord.eu/essential_grid/arsi/)



<http://www.ece.rutgers.edu/node/1135>



[https://ara.cse.unr.edu/?page\\_id=183](https://ara.cse.unr.edu/?page_id=183)

# How to Teach Robots to Inspect?

- Challenge: large amount of data
  - Rapid and accurate decision-making
- Existing works: Supervised Learning (Koch et al. 2015)
  - Shallow methods
    - SVM, Random Forrest, etc. (Prasanna et al. 2012, 2016)
  - Deep methods (Soukup and Huber-Mork 2014; Protopapadakis and Doulamis 2015; Zhang et al. 2016)
    - Convolutional Neural Networks (CNN)

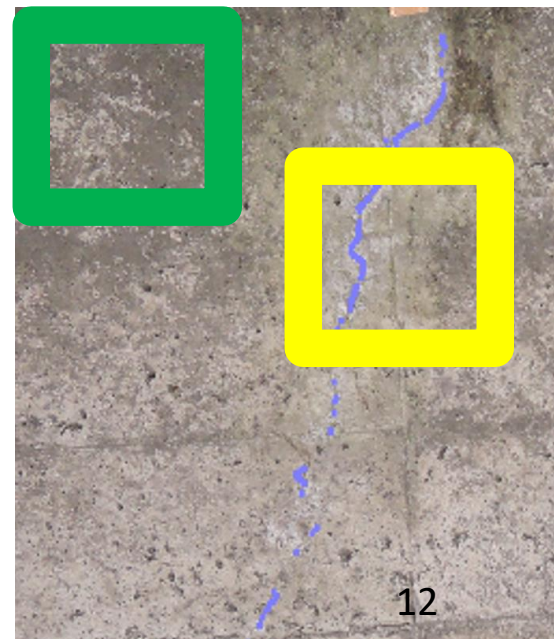
# Problems of Existing Methods

- Shallow methods
  - Feature engineering
    - Hand-crafted features
    - Tedious for many tasks
    - May require expert knowledge
- Deep methods
  - Requires large amount of labeled data
    - Need time/money/experts



# Our Problem Formulation

- Input: image patch  $x$   $\xrightarrow{\quad} y = f_{\theta}(x)$
- Output: defect probability  $\mathbf{y} = [y_0, y_1]$
- Our contributions
  - ResNet (He et al. 2015) for four types of defect detection
  - Active learning (Settles 2010) for training, with a novel sampling strategy

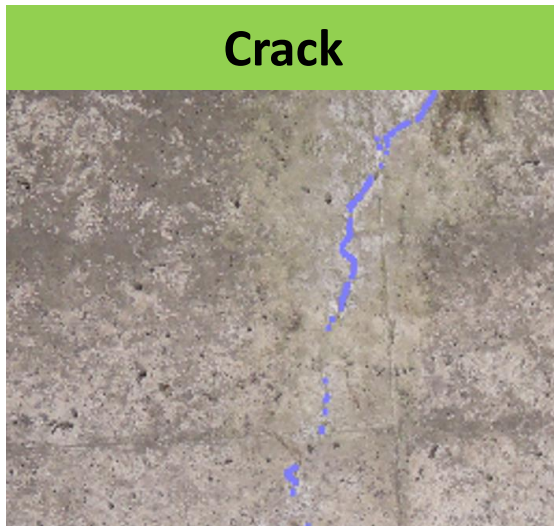


# Deep Residual Learning

- ResNet as the classifier  $\mathbf{y} = f_{\theta}(x)$ 
  - $\mathbf{z}_1 = f_{\theta_1}(x) + x, \dots, \mathbf{z}_n = f_{\theta_n}(\mathbf{z}_{n-1}) + \mathbf{z}_{n-1}$
  - $\mathbf{y} = f_{\theta_{n+1}}(\mathbf{z}_n) + \mathbf{z}_n$
  - Efficient learning of a deeper network (30+ layers)
- Loss Function: weighted cross-entropy loss
  - $E = \frac{-1}{N} \sum_{n=1}^N w(l_n) \log(y_{n,l_n})$
  - Handle unbalanced positive-negative ratio

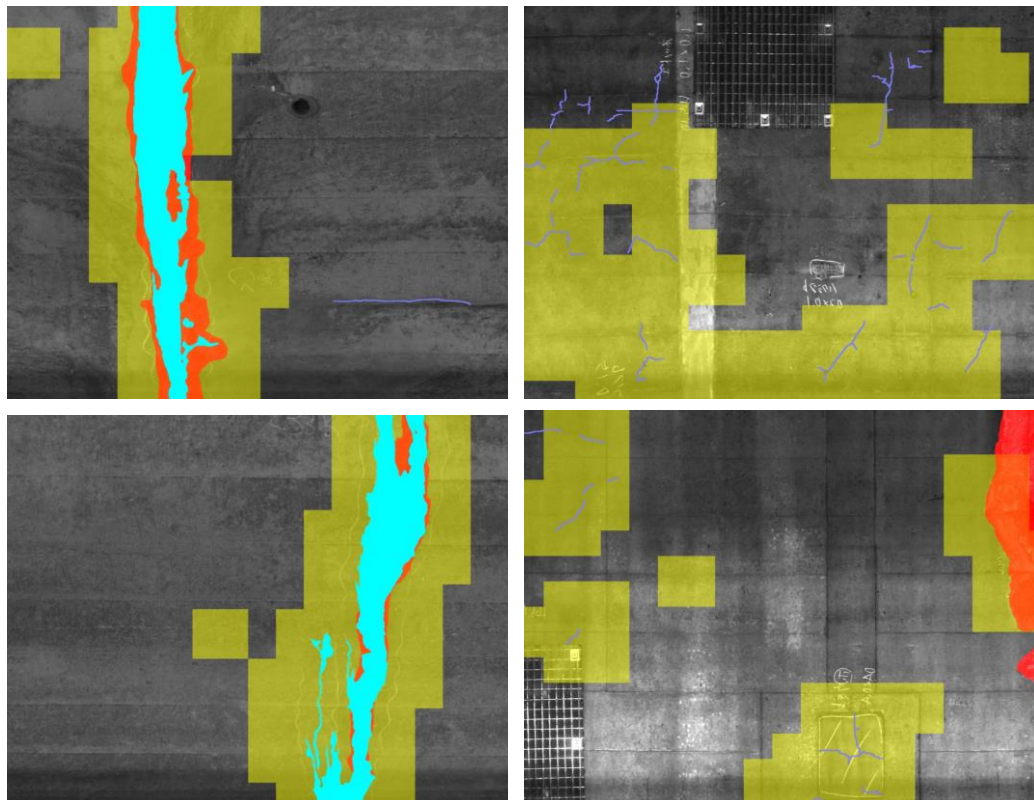
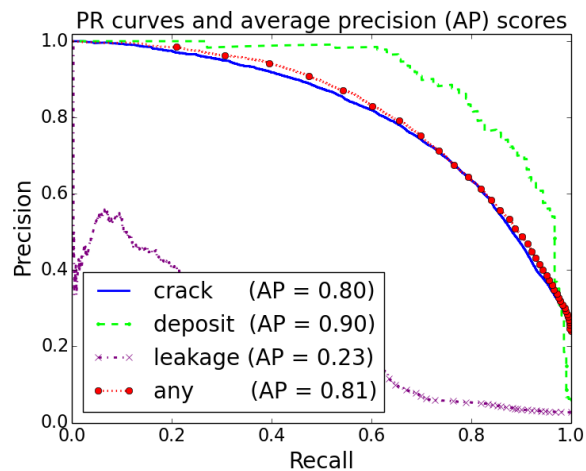
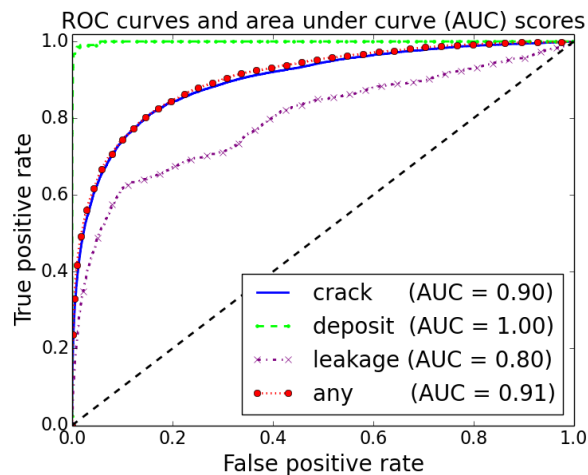
# Experiments

- Experimental Dataset: 289440 patches
  - Train : validation : test = 3 : 1 : 1
  - Train four classifiers



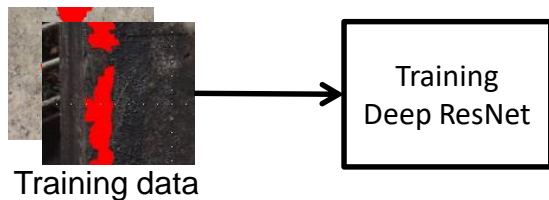


# Defect Detection Results



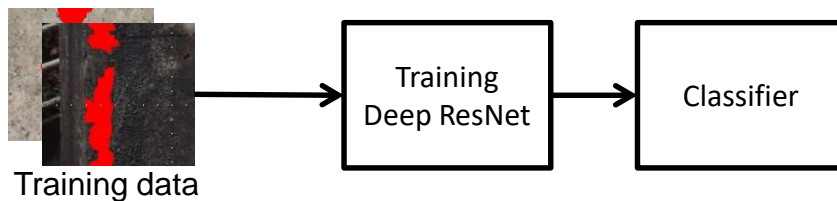
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- Data annotation for supervised learning
  - Tedious/expensive/qualified annotator
- AL: aims for the most efficient data annotation
  - Fewer data to achieve same accuracy



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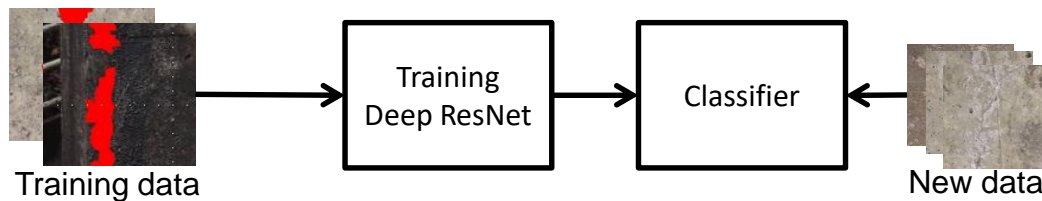
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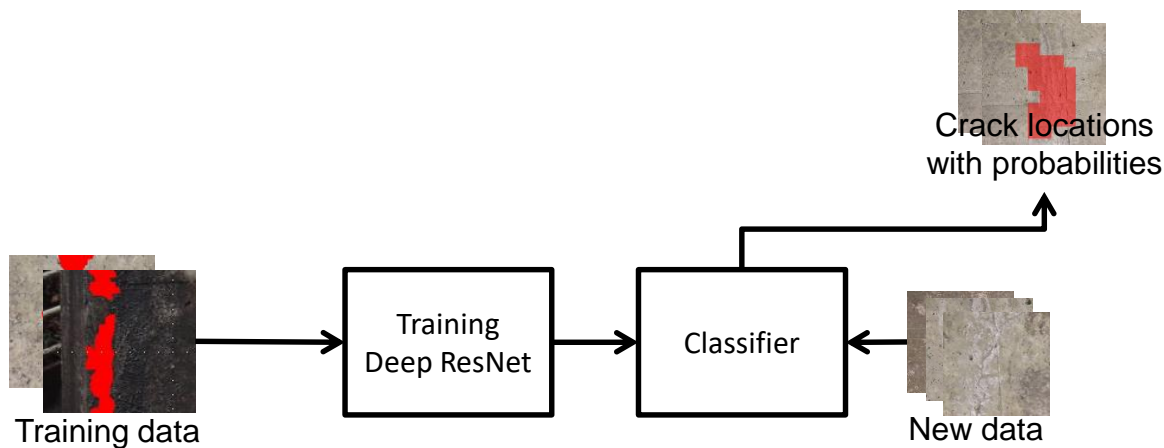
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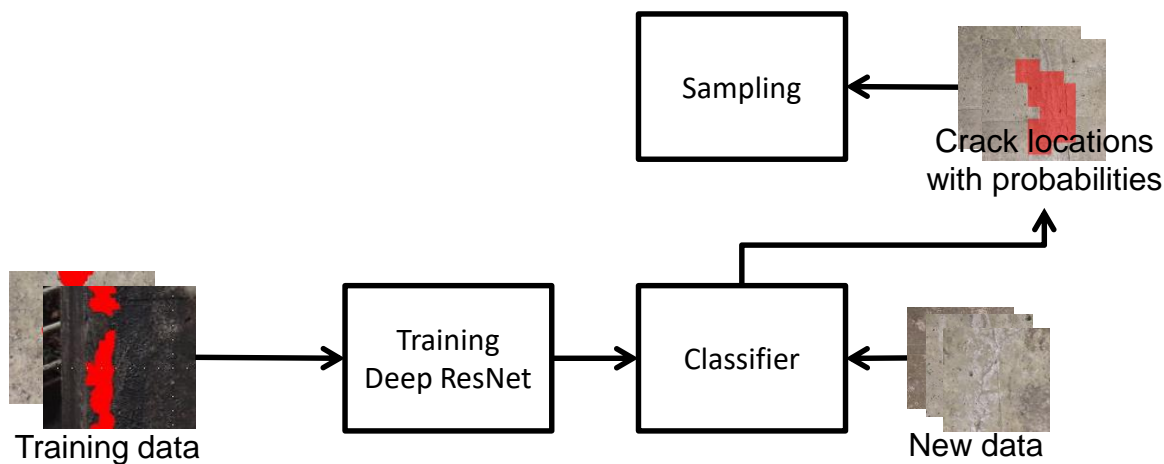
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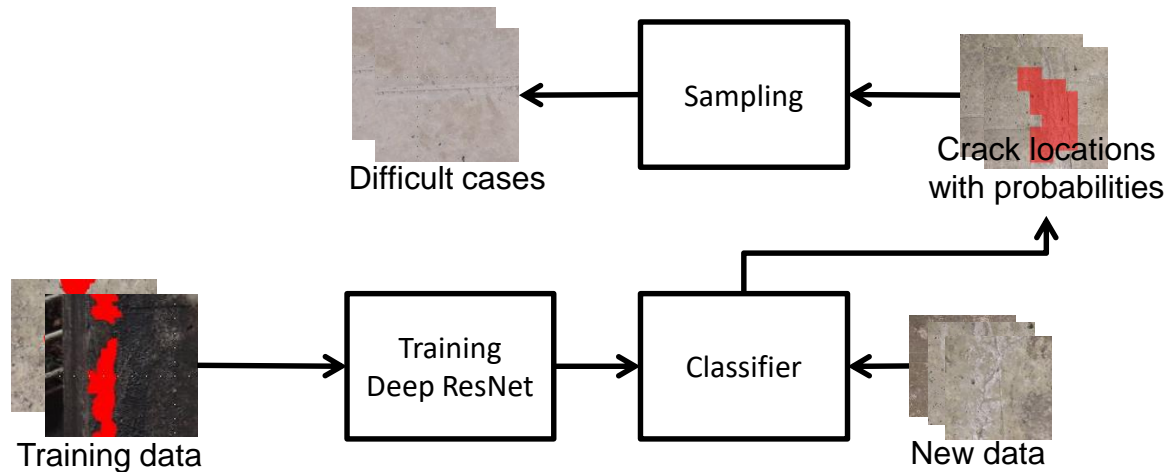
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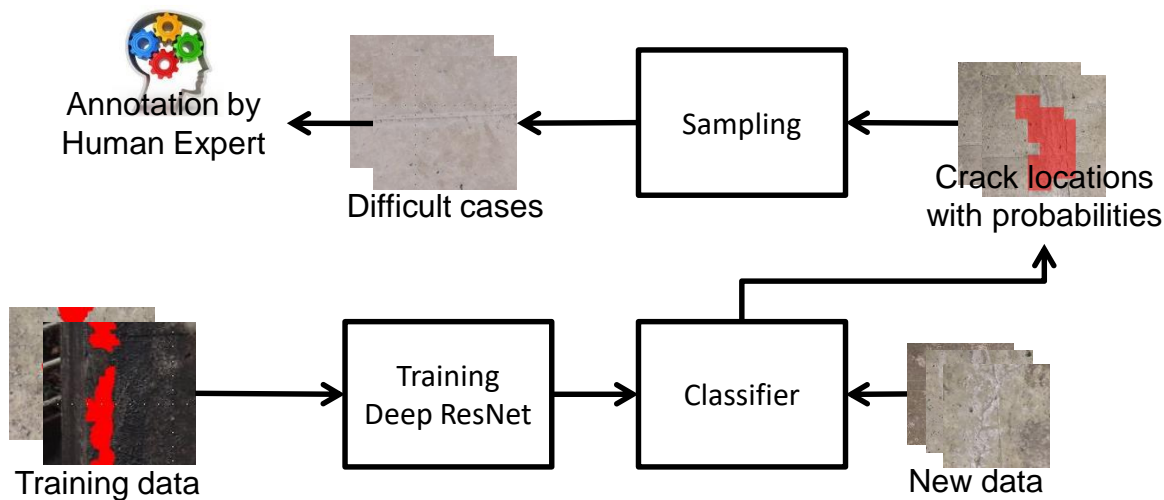
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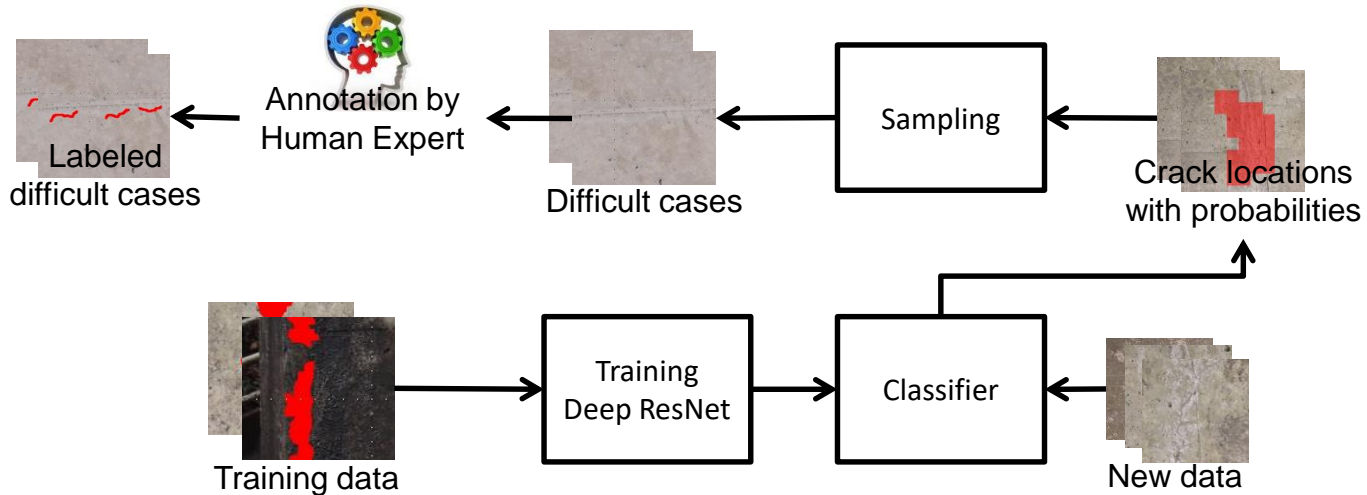
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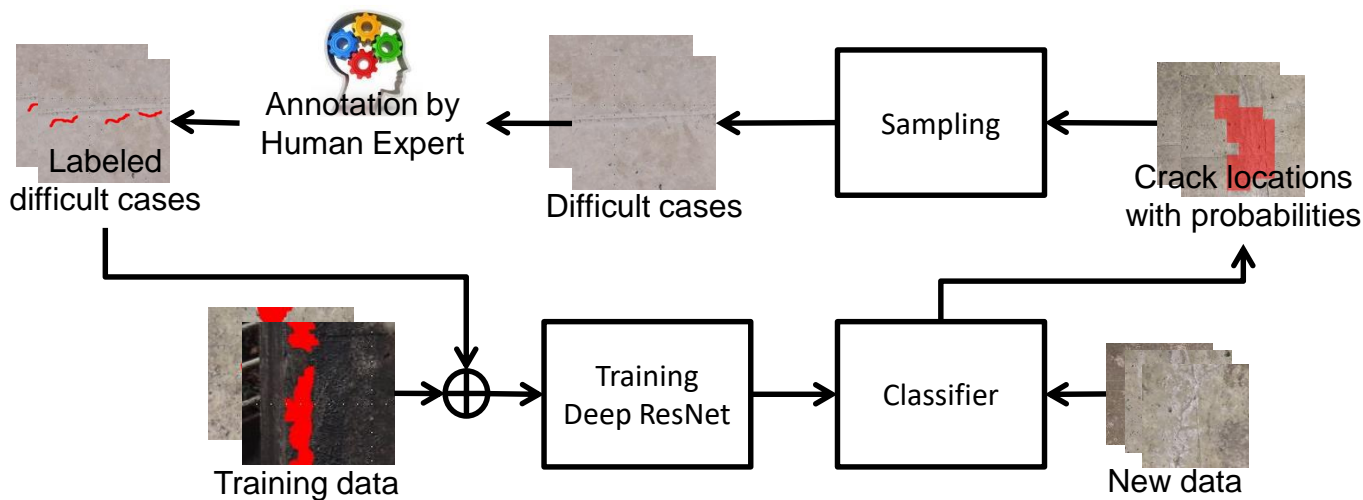
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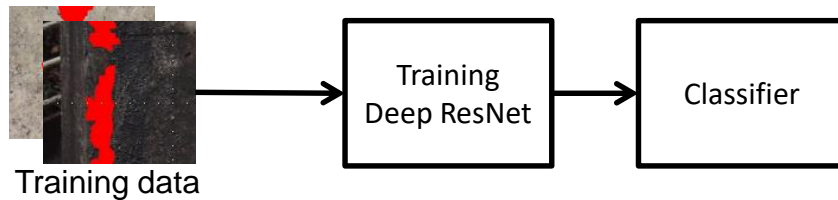


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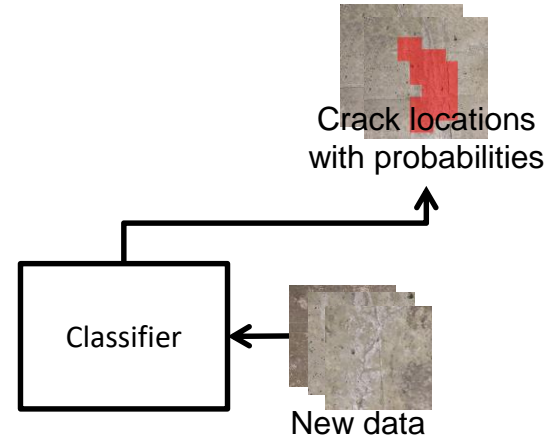
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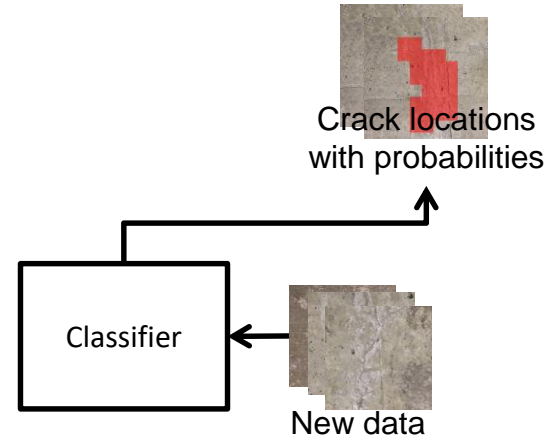
# AL Analogy: Initial Training



# AL Analogy: Trial and Error

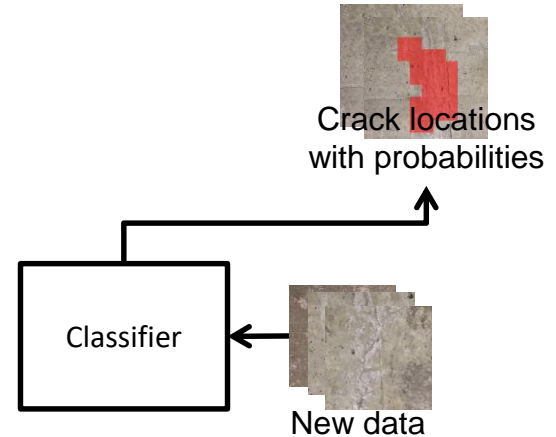


# AL Analogy: Trial and Error





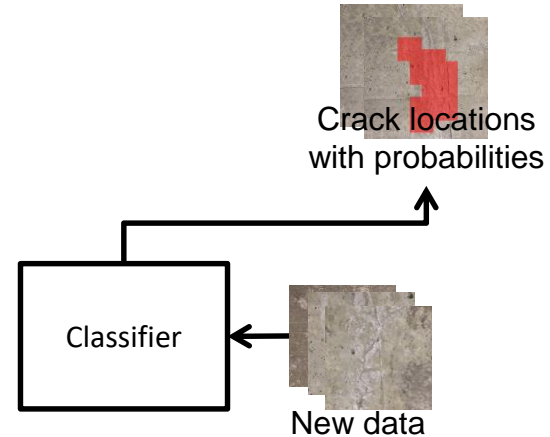
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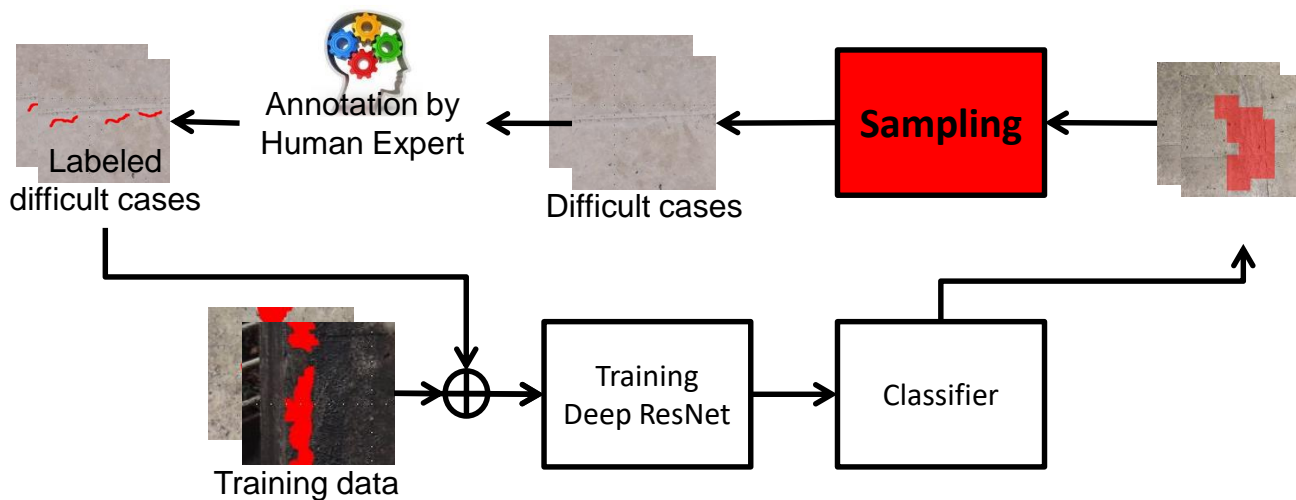
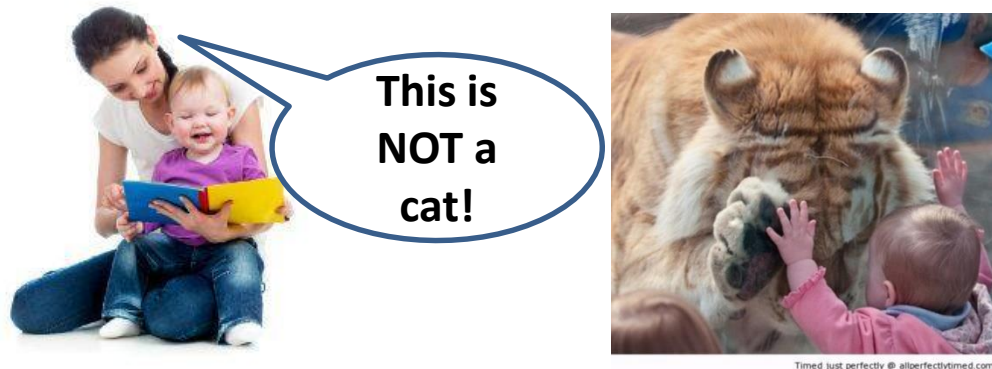
# AL Analogy: Trial and Error



Timed just perfectly @ allperfectlytimed.com

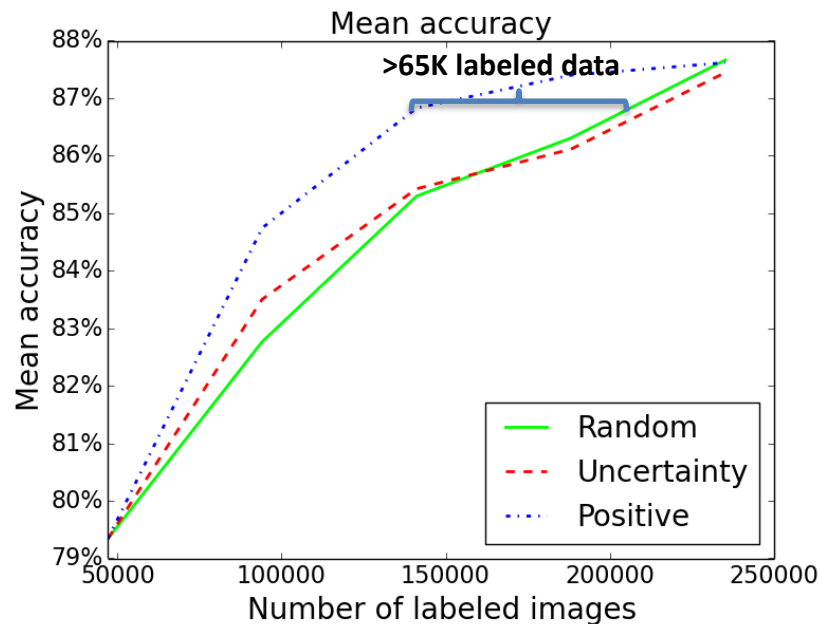


# AL Analogy: Selected Feedbacks



# Active Learning Results

- Positive AL
  - “Robot says this is defect, can you verify it?”
- Uncertainty AL
  - “Robot is not sure...”
- Test AL on “any” detector
  - “train+validation”
  - Positive AL saves 30%

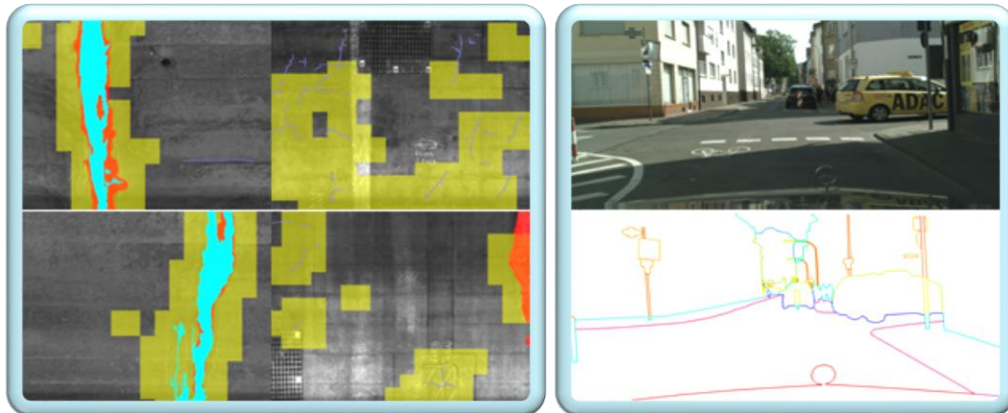


# Recap: Deep Active Learning

- Defect detection is important for civil infrastructure
- Deep Learning avoids explicit feature engineering
  - Need more data
- ResNet allows deeper networks for higher accuracy
- Active learning samples most informative data to improve classifier
  - Positive sampling strategy for defect detection



# Thank you! Questions?



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